

IML Robot Selection Worksheet

Project details, entry path and handling sequence

Download, fill and save a copy in your PDF reader. Complete the available details and identify reference drawings or open questions. Use the project-review link for the next step.

Company (optional)

Contact email (optional)

Project reference

Configuration under review (if known)

01 Entry path

Mark the entry and takeout paths on the actual machine and mold layout.

02 Mold-open task

State the target cycle and mold-open/ejector sequence; review the complete product handling sequence.

03 Product handoff

Show the planned container formats, takeout path and receiving position on the cell layout.

Planning inputs only. This worksheet does not confirm a robot model, machine/mold fit, supply scope, cycle time or acceptance. Leave unverified results blank.

IML Robot Selection Worksheet

Product, machine and review scope

Project reference (continued)

04 Product and mold

Provide product and label drawings, cavity layout, tooling dimensions, opening and ejection details.

05 Machine and site

Provide the exact machine model, mounting/site layout and interface documents; identify retained connections.

06 Scope and checks

Record the samples, configuration, operating conditions, results and unresolved items for each agreed check.

Additional notes / drawing references

Planning inputs only. This worksheet does not confirm a robot model, machine/mold fit, supply scope, cycle time or acceptance. Leave unverified results blank.

Source guide: www.hecostech.com/side-entry-vs-top-entry-impl-robot/

Project review: www.hecostech.com/contact-us/#engineering-proposal

info@hecostech.com